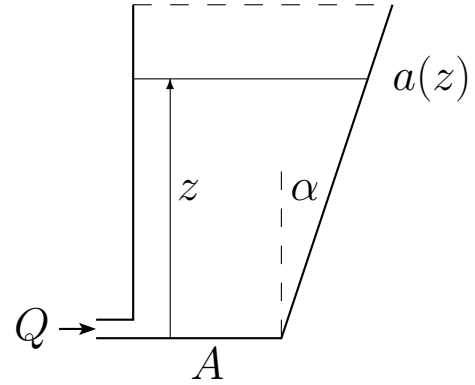
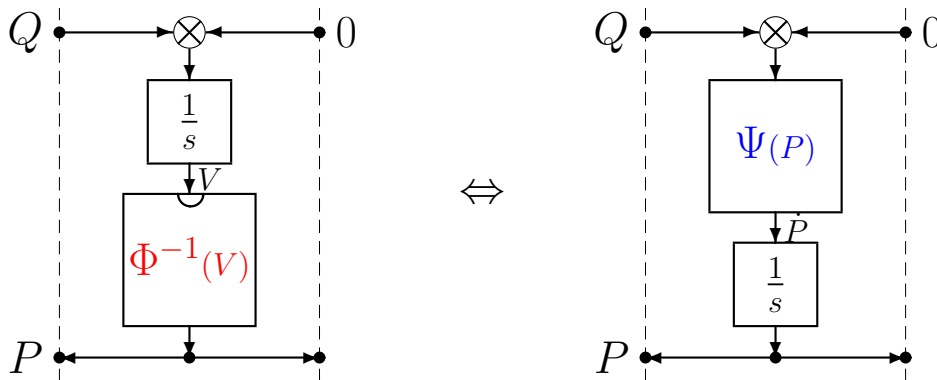


• Example. Tank with variable section.

- Q input volume flow rate
- P input pressure
- V volume of liquid in the tank
- z height of the liquid
- $a(z)$ area of the liquid at height z
- A area of the base section
- α slope of the liquid area
- p_0 pressure per unit of height



• Two equivalent POG block schemes can be used:



• The area of the liquid $a(z)$ at height z and the volume of liquid V are:

$$a(z) = A + \alpha z, \quad V = \int_0^z a(z) dz = A z + \frac{\alpha z^2}{2}$$

• Since $P = p_0 z$, the constitutive relation $V = \Phi(P)$ is defined as follows:

$$z = \frac{P}{p_0}, \quad V = \Phi(P) = A \frac{P}{p_0} + \frac{\alpha P^2}{2p_0^2}.$$

• The inverse function $P = \Phi^{-1}(V)$ is defined as follows:

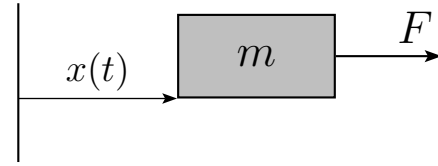
$$P = \Phi^{-1}(V) = p_0 \frac{\sqrt{A^2 + 2\alpha V} - A}{\alpha}$$

• It can be proved that function $\Psi(P)$ can be obtained as follows:

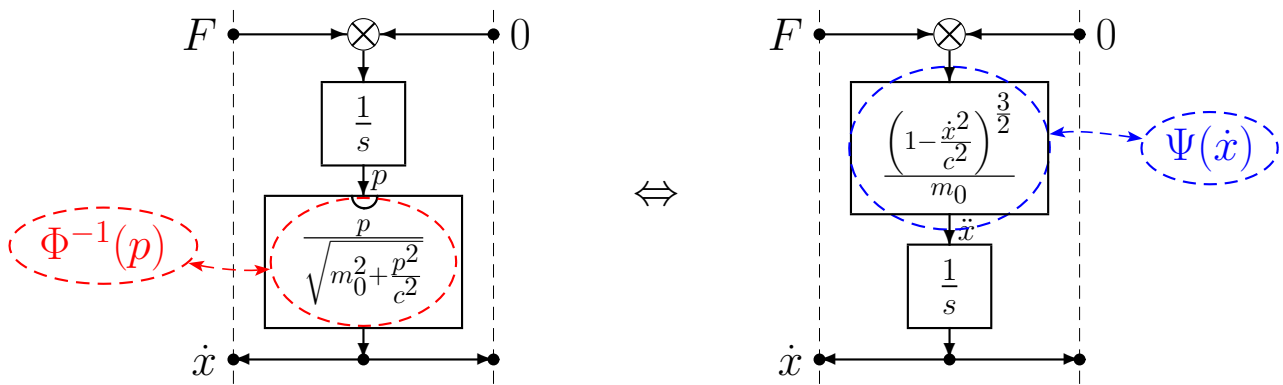
$$\Psi(P) = \left[\frac{\partial \Phi(P)}{\partial P} \right]^{-1} = \left[\frac{A}{p_0} + \frac{\alpha P}{p_0^2} \right]^{-1} = \frac{p_0^2}{A p_0 + \alpha P}$$

• Example. A translating mass.

- x position of the mass
- \dot{x} velocity of the mass
- m value of the mass
- m_0 value of the mass at rest
- c velocity of the light
- p momentum of the mass



• The system can be described using one of the following POG schemes:



• Taking into account the relativistic effects, mass m and $p = \Phi(\dot{x})$ are:

$$m = \frac{m_0}{\sqrt{1 - \frac{\dot{x}^2}{c^2}}}, \quad p = \Phi(\dot{x}) = m \dot{x} = \frac{m_0 \dot{x}}{\sqrt{1 - \frac{\dot{x}^2}{c^2}}}$$

• The inverse function $\Phi^{-1}(p)$ can be expressed as follows:

$$\dot{x} = \Phi^{-1}(p) = \frac{p}{\sqrt{m_0^2 + \frac{p^2}{c^2}}}$$

• Function $\Psi(\dot{x})$ can be computed as follows:

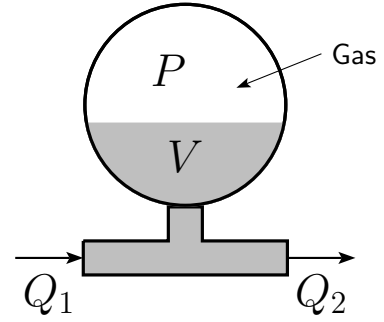
$$\Psi(\dot{x}) = \left[\frac{\partial \Phi(\dot{x})}{\partial \dot{x}} \right]^{-1} = \left[\frac{m_0}{\left(1 - \frac{v^2}{c^2}\right)^{\frac{3}{2}}} \right]^{-1} = \frac{\left(1 - \frac{v^2}{c^2}\right)^{\frac{3}{2}}}{m_0}$$

• The energy E_s stored in the system can be expressed as follows:

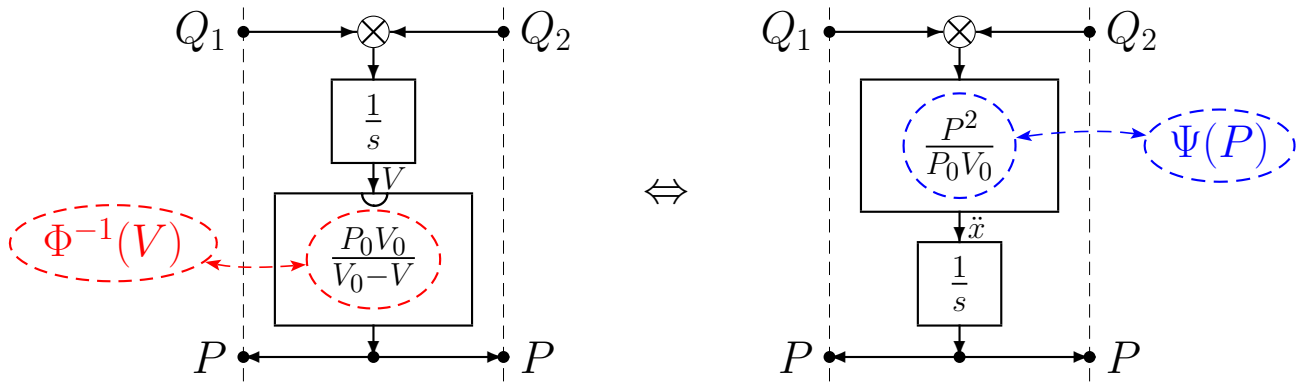
$$E_s = \int_0^p \Phi^{-1}(p) dp = \int_0^p \frac{p}{\sqrt{m_0^2 + \frac{p^2}{c^2}}} dp = m_0 c^2 \left[\sqrt{1 + \frac{p^2}{m_0^2 c^2}} - 1 \right]$$

• Nonlinear hydraulic capacitor.

- Q_1 input volume flow rate
- Q_2 output volume flow rate
- P pressure of the capacitor
- V volume of liquid within the capacitor
- V_G volume of gas within the capacitor
- P_0 pressure of the empty capacitor
- V_0 volume of the empty capacitor



• The system can be described using the following POG schemes:



• The gas pressure P within the capacitor satisfies the following equation:

$$P V_G = P_0 V_0, \quad V_G = V_0 - V \quad \rightarrow \quad P = \Phi^{-1}(V) = \frac{P_0 V_0}{V_0 - V}$$

• The constitutive equation of the nonlinear hydraulic capacitor is:

$$V = \Phi(P) = V_0 - \frac{P_0 V_0}{P}$$

• Function $\Psi(P)$ can be computed as follows:

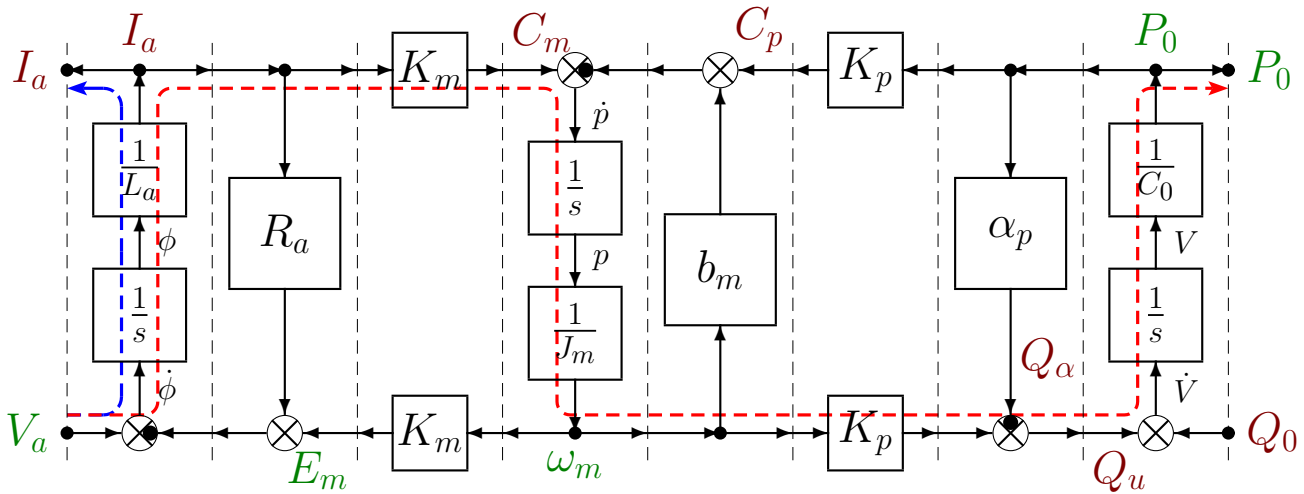
$$\Psi(P) = \left[\frac{\partial \Phi(P)}{\partial P} \right]^{-1} = \left[\frac{P_0 V_0}{P^2} \right]^{-1} = \frac{P^2}{P_0 V_0}$$

• The energy E_s stored in the system can be expressed as follows:

$$E_s = \int_0^V \Phi^{-1}(p) dp = \int_0^V \frac{P_0 V_0}{V_0 - V} dV = P_0 V_0 \ln \frac{V_0}{(V_0 - V)}$$

Relative degree of a transfer function $G(s)$

- Let us consider a generic block scheme:



- For each transfer function $G(s) = \frac{Y(s)}{U(s)}$ which links an input $u(t)$ to the output $y(t)$, the following properties hold:

- 1) the order of function $G(s)$ is equal to the number n of independent dynamic elements which store energy within the system;
- 2) the poles of function $G(s)$ are equal to the solutions of equation $\Delta(s) = 0$ where $\Delta(s)$ is the determinant of the block scheme;
- 3) the **relative degree** of function $G(s)$ is equal to the minimum number r of integrators which is present in the set of all the paths that links the input $u(t)$ to the output $y(t)$;
- 4) if there is only one path \mathcal{P}_1 that links the input $u(t)$ to the output $y(t)$, then the zeros of function $G(s)$ are equal to the solutions of equation $\Delta_1(s) = 0$ where $\Delta_1(s)$ is the determinant of the reduced block scheme obtained from the original one eliminating all the blocks touched by the path \mathcal{P}_1 ;

$G(s) = \frac{P_0}{V_a}$ has 3 poles and 0 zeros because the relative degree is $r = 3$;

$G(s) = \frac{I_a}{V_a}$ has 3 poles and 2 zeros because the relative degree is $r = 1$;

- Note:** the higher is the relative degree the more difficult is the control.